

Uncertainty Relations in the Presence of Quantum Memory for Mutually Unbiased Measurements

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Joint work with Nan Wu and Fangmin Song (arXiv:1807.01047)

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Outline

Preliminary

- Uncertainty relation

- Mutually unbiased measurements (MUM)

- Conditional collision entropy

An equality relation for complete set of MUMs

Implications of the equality relation

- Guessing game

- Uncertainty relation

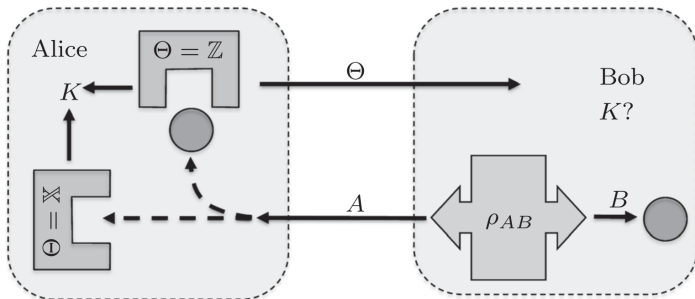
- Entanglement detection

Open Problems and Summaries

- The CQC conjecture

- Summary

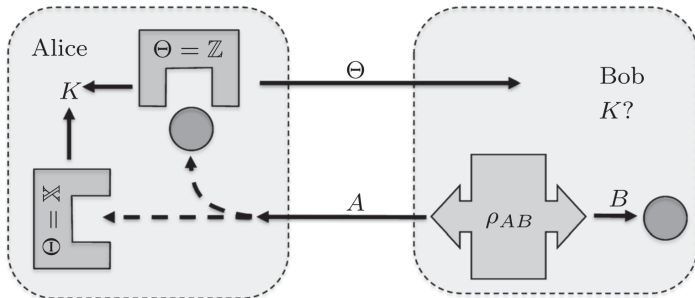
Guessing game



- ▶ A guessing game¹ played by Alice and Bob
 1. Bob prepares state ρ_{AB} and sends ρ_A to Alice
 2. Alice measures either \mathbb{X} or \mathbb{Z} (uniformly) and stores outcome K
 3. Alice tells Bob which measurement Θ has been conducted
 4. Bob guesses the value of K
- ▶ \mathbb{X} and \mathbb{Z} are known to both Alice and Bob
- ▶ How well can Bob guess K on average?

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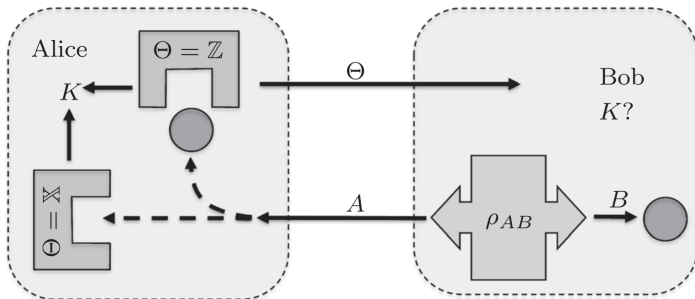
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Entanglement helps!

- ▶ Assume $\mathbb{X} = \{|x_i\rangle\}$ and $\mathbb{Z} = \{|z_j\rangle\}$ be complementary on A :
 $|\langle x_i | z_j \rangle| = 1/\sqrt{d}$ for arbitrary i, j
- ▶ Suppose Bob prepares a maximally entangled state

$$|\Psi\rangle_{AB} = \frac{1}{\sqrt{d}} \sum_i |x_i\rangle_A |x_i\rangle_B = \frac{1}{\sqrt{d}} \sum_j |z_j\rangle_A |z_j\rangle_B$$

and sends ρ_A to Alice

- ▶ Measuring ρ_A with \mathbb{X}/\mathbb{Z} , Alice gets classical-quantum (cq.) states

$$\begin{aligned}\omega_{XB} &= \frac{1}{d} \sum_i |x_i\rangle\langle x_i|_A \otimes |x_i\rangle\langle x_i|_B \\ \tau_{ZB} &= \frac{1}{d} \sum_j |z_j\rangle\langle z_j|_A \otimes |z_j\rangle\langle z_j|_B\end{aligned}$$

- ▶ If Alice obtains x_i , Bob processes state x_i . Similar for \mathbb{Z}
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Uncertainty relation (in the presence of memory)

- ▶ How much can the entanglement reduce uncertainty?
- ▶ That is, what if Bob prepares an arbitrary state ρ_{AB} ?
- ▶ Measuring ρ_A with \mathbb{X}/\mathbb{Z} , Alice gets two cq. states

$$\omega_{XB} = \sum_i p_i |x_i\rangle\langle x_i| \otimes \omega_i^B, \quad p_i = \text{Tr}\langle x_i | \rho_{AB} | x_i \rangle,$$

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- ▶ To answer this question, we must know
 1. How to quantify the entanglement of ρ_{AB} ?
 2. How to quantify the uncertainty of ω_{XB} and τ_{ZB} ?
- ▶ Uncertainty relation in the presence of memory (UR)²

$$H(X|B)_\omega + H(Z|B)_\tau \geq \log d + H(A|B)_\rho$$

- ▶ $H(A|B)_{\omega, \tau, \rho}$ is the conditional entropy of state ω , τ , and ρ
- ▶ $H(A|B)$ quantifies the uncertainty about A given knowledge of B

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Ingredients of a uncertainty relation

$$H(X|B)_\omega + H(Z|B)_\tau \geq \log d + H(A|B)_\rho$$

- ▶ Five ingredients of a general uncertainty relation

Incompatible measurements: \mathbb{X} and \mathbb{Z}

State being measured: bipartite state ρ_{AB}

Uncertainty measure: conditional entropy $H(A|B)_{\omega,\tau}$

Uncertainty relation form: lower bound on sum of uncertainties

Entanglement measure: conditional entropy $H(A|B)_\rho$

- ▶ Our relation

Incompatible measurements: complete set of mutually unbiased measurements

State being measured: bipartite state ρ_{AB}

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Uncertainty relation form: an equality

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Mutually unbiased measurements

- ▶ Let $\mathcal{P}^{(1)} = \{P_x^{(1)}\}_{x \in [d]}$ and $\mathcal{P}^{(2)} = \{P_x^{(2)}\}_{x \in [d]}$ be two POVMs:

$$\forall \theta = 1, 2, \quad P_x^{(\theta)} \geq 0, \quad \sum_x P_x^{(\theta)} = \mathbb{1}$$

- ▶ They are mutually unbiased³ if for all $x, x' \in [d], \theta = 1, 2$

$$\mathrm{Tr} \left[P_x^{(\theta)} \right] = 1, \quad \text{each operator is normalized}$$

$$\mathrm{Tr} \left[P_x^{(1)} P_x^{(2)} \right] = \frac{1}{d}, \quad \text{two measurements are unbiased}$$

$$\mathrm{Tr} \left[P_x^{(\theta)} P_{x'}^{(\theta)} \right] = \delta_{x,x'} \kappa + (1 - \delta_{x,x'}) \frac{1 - \kappa}{d - 1}.$$

- ▶ The *efficiency parameter* κ satisfies $1/d < \kappa \leq 1$
- ▶ $\{\mathcal{P}^{(\theta)}\}_{\theta \in \Theta}$ forms a set of MUMs if they are pairwise unbiased
- ▶ A complete set of MUMs is a set of MUMs of size $d + 1$
- ▶ A complete set of MUMs can be explicitly constructed³

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Conditional collision entropy

- ▶ Let ρ_{AB} be a quantum state on system AB
- ▶ The conditional collision entropy is defined as⁴

$$H_2(A|B)_\rho = -\log \text{Tr} \left[\rho_{AB}(\mathbb{1}_A \otimes \rho_B)^{-1/2} \rho_{AB}(\mathbb{1}_A \otimes \rho_B)^{-1/2} \right]$$

- ▶ $\mathbb{1}_A$ is the identity operator
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Post-measurement state for a MUM

- ▶ Let $\mathcal{P}^{(\theta)} = \{P_x^{(\theta)}\}_{x \in [d]}$ be a MUM in A
- ▶ Measuring ρ_{AB} on A by $\mathcal{P}^{(\theta)}$, we get a cq. state

$$\omega_{X^{(\theta)}B} = \sum_{x=1}^d |x\rangle\langle x|_X \otimes \text{Tr}_A \left[\left(P_x^{(\theta)} \otimes \mathbb{1}_B \right) \rho_{AB} \right] \quad (1)$$

- ▶ Register X stores the measurement outcome
- ▶ $\text{Tr}_A[(P_x^{(\theta)} \otimes \mathbb{1}_B)\rho_{AB}]$ is the post-measurement state (unnormalized) left on system B
- ▶ $\text{Tr}[(P_x^{(\theta)} \otimes \mathbb{1}_B)\rho_{AB}]$ is probability that the outcome is x

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Post-measurement state for complete set of MUMs

- ▶ Let $\{\mathcal{P}^{(\theta)}\}_{\theta \in [d+1]}$ be a complete set of MUMs on system A
- ▶ Define the following cq. state

$$\omega_{XB\Theta} = \frac{1}{d+1} \sum_{\theta=1}^{d+1} \sum_{x=1}^d |x\rangle\langle x|_X \otimes \text{Tr}_A \left[\left(P_x^{(\theta)} \otimes \mathbb{1}_B \right) \rho_{AB} \right] \otimes |\theta\rangle\langle \theta|_{\Theta} \quad (2)$$

- ▶ Θ indicates which MUM has been performed
- ▶ $\omega_{XB\Theta}$ is a uniform mixing of $\omega_{X^{(\theta)}B}$: $\omega_{XB\Theta=\theta} = \omega_{X^{(\theta)}B}$
- ▶ Conditional collision entropy of $\omega_{XB\Theta}$, with partition $X:B\Theta$

$$H_2(X|B\Theta)_{\omega} = -\log \left(\frac{1}{d+1} \sum_{\theta,x} \text{Tr}_B \left\{ \text{Tr}_A [P_x^{(\theta)} \tilde{\rho}_{AB}]^2 \right\} \right)$$

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Theorem (An equality relation for complete set of MUMs)

Let $\{\mathcal{P}^{(\theta)}\}_{\theta \in [d+1]}$ be a complete set of MUMs on system A . For arbitrary quantum state ρ_{AB} , it holds that

$$H_2(A|B\Theta)_\omega = \log(d+1) - \log\left(f(\kappa) + g(\kappa)2^{-H_2(A|B)_\rho}\right), \quad (3)$$

where $\omega_{XB\Theta}$ is defined in Eq. (2), and the coefficients are given by

$$f(\kappa) = 1 + \frac{1-\kappa}{d-1}, \quad g(\kappa) = \frac{\kappa d - 1}{d-1}.$$

- ▶ When $\kappa = 1$, Eq. (3) recovers the main result of [2]⁶

$$H_2(A|B\Theta)_\omega = \log(d+1) - \log\left(1 + 2^{-H_2(A|B)_\rho}\right)$$

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Pretty-good state discrimination

- ▶ **State discrimination:** Let $\mathcal{S} = \{p_i, \rho_i\}$ be a state ensemble. Sample σ from \mathcal{S} . What is the index i of σ ?
- ▶ Perform a measurement $\mathcal{M} = \{M_i\}$ to extract index: if the measurement outcome is i , then assert $\sigma \equiv \rho_i$
- ▶ Finding optimal measurement is a complex optimization problem⁷
- ▶ **Pretty-good measurement**⁸ $\mathcal{M}^{\text{PG}} = \{M_i\}$ of \mathcal{S} :
 $M_i = \rho^{-1/2}(p_i\rho_i)\rho^{-1/2}$, where $\rho = \sum_i p_i\rho_i$
- ▶ Pretty-good guessing probability

$$P^{\text{PG}}(\mathcal{S}) = \sum_i p_i^2 \text{Tr}[\rho^{-1/2}\rho_i\rho^{-1/2}\rho_i]$$

- ▶ \mathcal{S} is equivalent to a cq. state $\rho_{XB} = \sum_i p_i|i\rangle\langle i| \otimes \rho_i^B$
- ▶ Operational interpretation of the conditional collision entropy⁹

$$P^{\text{PG}}(X|B)_\rho \equiv P^{\text{PG}}(\mathcal{S}) = 2^{-H_2(X|B)_\rho}$$

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Pretty-good state discrimination

- ▶ **State discrimination:** Let $\mathcal{S} = \{p_i, \rho_i\}$ be a state ensemble. Sample σ from \mathcal{S} . What is the index i of σ ?
- ▶ Perform a measurement $\mathcal{M} = \{M_i\}$ to extract index: if the measurement outcome is i , then assert $\sigma \equiv \rho_i$
- ▶ Finding optimal measurement is a complex optimization problem⁷
- ▶ **Pretty-good measurement**⁸ $\mathcal{M}^{\text{pg}} = \{M_i\}$ of \mathcal{S} :
 $M_i = \rho^{-1/2}(p_i\rho_i)\rho^{-1/2}$, where $\rho = \sum_i p_i\rho_i$
- ▶ Pretty-good guessing probability

$$P^{\text{pg}}(\mathcal{S}) = \sum_i p_i^2 \text{Tr}[\rho^{-1/2}\rho_i\rho^{-1/2}\rho_i]$$

- ▶ \mathcal{S} is equivalent to a cq. state $\rho_{XB} = \sum_i p_i|i\rangle\langle i| \otimes \rho_i^B$
- ▶ Operational interpretation of the conditional collision entropy⁹

$$P^{\text{pg}}(X|B)_\rho \equiv P^{\text{pg}}(\mathcal{S}) = 2^{-H_2(X|B)_\rho}$$

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Pretty-good guessing for a complete set of MUMs

- ▶ Each MUM induces a cq. state of the form

$$\omega_{X^{(\theta)}B} = \sum_{x=1}^d |x\rangle\langle x| \otimes \text{Tr}_A \left[\left(P_x^{(\theta)} \otimes \mathbb{1}_B \right) \rho_{AB} \right]$$

- ▶ How well can Bob guess x ?
 - ▶ He can guess “pretty-good”: $\text{PPG}(X^{(\theta)}|B)_\omega$
- ▶ How well can Bob guess x for a complete set of MUMs, on average?
- ▶ *Totally* determined by the quantum collision entropy of ρ_{AB}

Lemma

Let $\{\mathcal{P}^{(\theta)}\}_{\theta \in [d+1]}$ be a complete set of MUMs on system A . For arbitrary quantum state ρ_{AB} , it holds that

$$\sum_{\theta=1}^{d+1} \text{PPG} \left(X^{(\theta)} | B \right)_\omega = f(\kappa) + g(\kappa) 2^{-H_2(A|B)_\rho}.$$

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Lower bound on sum of uncertainties

- ▶ Uncertainty relations are commonly expressed as lower bound on the sum of uncertainties

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- ▶ This is a uncertainty relation without memory
- ▶ Recovers a special case ($\alpha = 2$) of **Proposition 3** in [9]¹⁰

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An entanglement detection method

- ▶ Let $\{\mathcal{P}^{(\theta)}\}_{\theta \in [d+1]}$ be a complete set of MUMs on A
- ▶ Let $\{\mathcal{Q}^{(\theta)}\}_{\theta \in [d+1]}$ be an arbitrary set of $d + 1$ measurements on B
- ▶ If Alice performs $\mathcal{P}^{(\theta)}$, Bob performs $\mathcal{Q}^{(\theta)}$. They get

$$\omega_{X^{(\theta)}Y^{(\theta)}} = \sum_{x,y=1}^d \text{Tr} \left[\left(P_x^{(\theta)} \otimes Q_y^{(\theta)} \right) \rho_{AB} \right] |x\rangle\langle x| \otimes |y\rangle\langle y|.$$

- ▶ $\omega_{X^{(\theta)}Y^{(\theta)}}$ can be evaluated from measurement statistics

Lemma

For arbitrary *separable* quantum state ρ_{AB} , it holds that

$$\frac{1}{d+1} \sum_{\theta=1}^{d+1} H_2 \left(X^{(\theta)} \middle| Y^{(\theta)} \right)_{\omega} \geq \log(d+1) - \log(f(\kappa) + g(\kappa)).$$

An entanglement detection method (cont.)

- ▶ How does the detection method work?
- ▶ Suppose now there exists a source producing states ρ_{AB}
- ▶ Alice and Bob sample from the source and gather statistics
- ▶ They estimate the joint distribution for each pair $\{\mathcal{P}^{(\theta)}, \mathcal{Q}^{(\theta)}\}$
- ▶ They evaluate the sum of (classical) conditional collision entropies
- ▶ According to the above lemma, the source is entangled if

$$\frac{1}{d+1} \sum_{\theta=1}^{d+1} \mathbb{H}_2 \left(X^{(\theta)} \middle| Y^{(\theta)} \right)_{\omega} < \log(d+1) - \log(f(\kappa) + g(\kappa)). \quad (5)$$

- ▶ The choice of measurements $\{\mathcal{Q}^{(\theta)}\}$ on system B is arbitrary
- ▶ For best detection criterion, minimize the LHS. of Eq. (5) by optimizing over all possible measurements $\{\mathcal{Q}^{(\theta)}\}$

Outline

Preliminary

- Uncertainty relation

- Mutually unbiased measurements (MUM)

- Conditional collision entropy

An equality relation for complete set of MUMs

Implications of the equality relation

- Guessing game

- Uncertainty relation

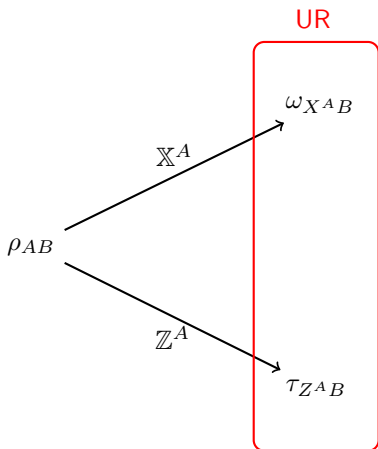
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Open Problems and Summaries

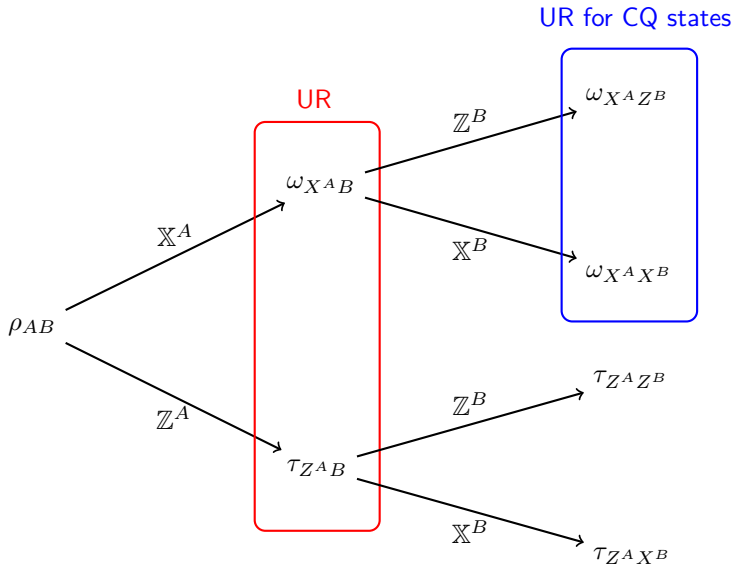
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- Summary

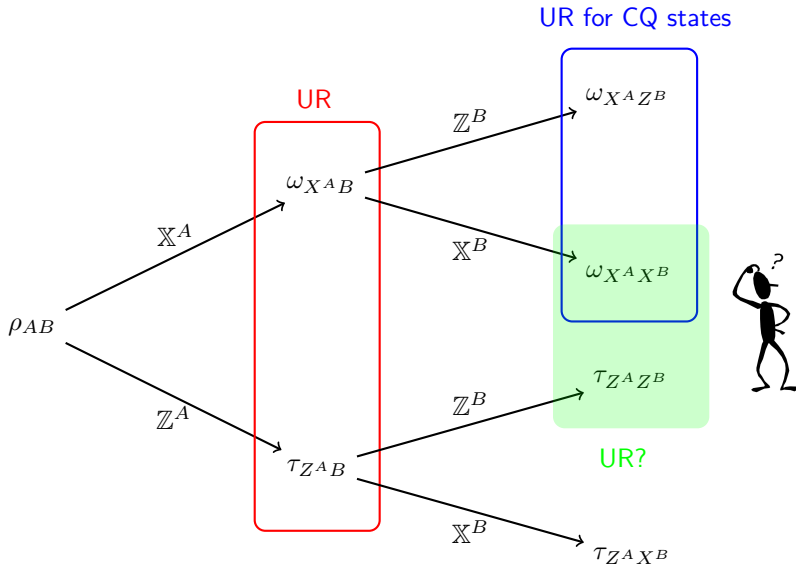
A unified view



A unified view (cont.)



A unified view (cont.)



CQC conjecture

- ▶ Let \mathbb{X}^A and \mathbb{Z}^A be complementary on A
- ▶ Let \mathbb{X}^B and \mathbb{Z}^B be complementary on B
- ▶ $\mathbb{X}^A \otimes \mathbb{X}^B$ and $\mathbb{Z}^A \otimes \mathbb{Z}^B$ induce two classical states

$$\omega_{X^A X^B} = \sum_{ij} p_{ij} |x_i^A\rangle \langle x_i^A| \otimes |x_j^B\rangle \langle x_j^B|$$

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- ▶ The complementary-quantum correlation conjecture (CQC)¹¹

$$I(X^A: X^B)_\omega + I(Z^A: Z^B)_\tau \leq I(A:B)_\rho$$

- ▶ $I(A:B)$ is the mutual information quantifying the correlation between A and B

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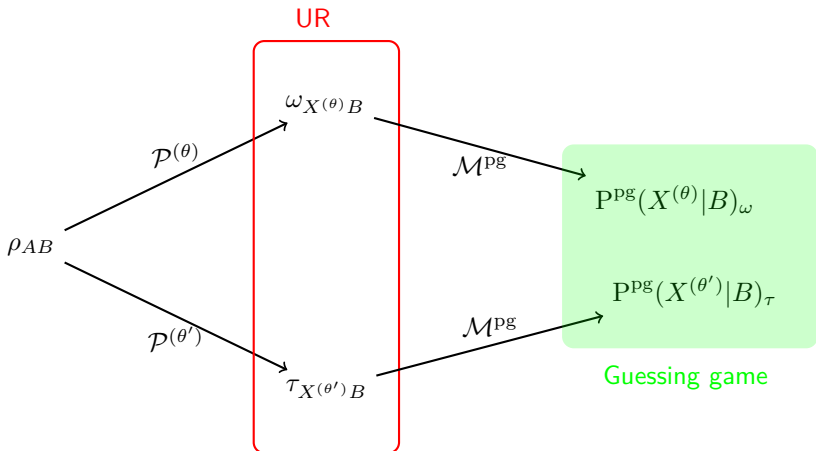
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Our work fits into the unified view



Summary

▶ **What have done?**

- ▶ An equality relation for complete set of MUMs
- ▶ Conditional collision entropy as uncertainty measure
- ▶ Some corollaries from the equality relation
 1. Bound on pretty-good guessing probabilities
 2. An uncertainty relation expressed as sum of uncertainties
 3. An entanglement detection method

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Thank you !

Any questions ?

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